#### PC hardware and x86

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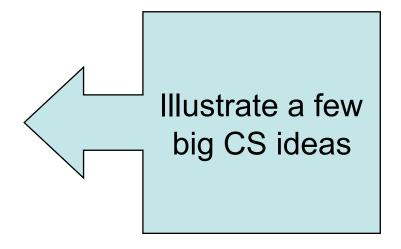
#### A PC



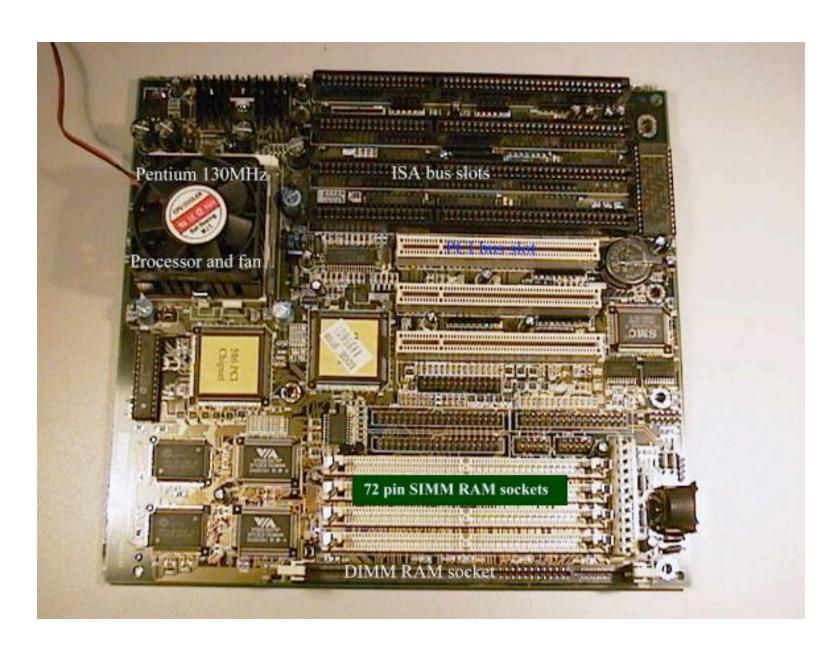
how to make it to do something useful?

#### Outline

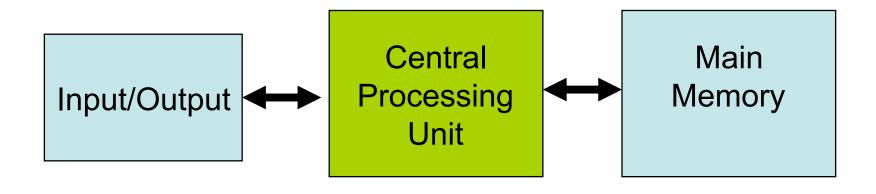
- PC architecture
- x86 instruction set
- gcc calling conventions
- PC emulation



#### PC board

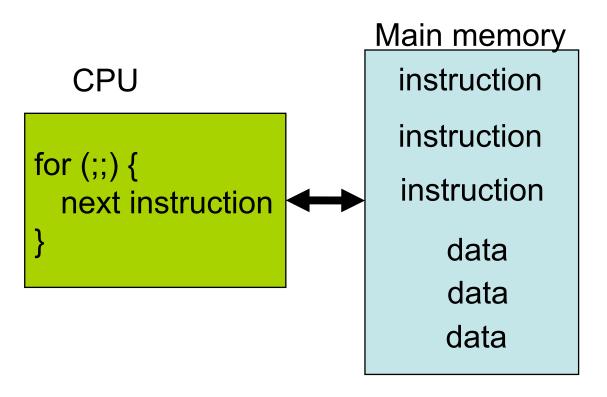


#### The von Neumann model



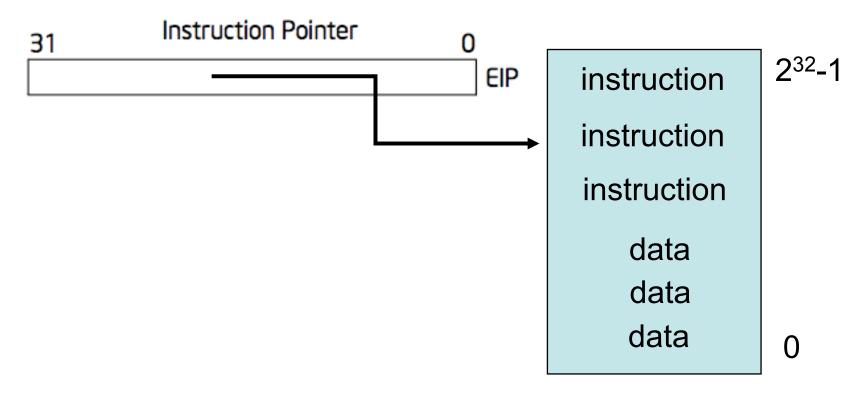
- I/O: communicating data to and from devices
- CPU: digital logic for performing computation
- Memory: N words of B bits

## The stored program computer



- Memory holds instructions and data
- CPU interpreter of instructions

#### x86 implementation



- EIP is incremented after each instruction
- Instructions are different length
- EIP modified by CALL, RET, JMP, and conditional JMP

#### Registers for work space

#### **General-Purpose Registers**

31	16	15	8	7	0	16-bit	32-bit
		AH		AL		AX	EAX
		BH		BL		BX	EBX
		CH		CL		CX	ECX
		DH		DL		DX	EDX
			BF	)			EBP
			SI				ESI
			DI				EDI
			SF	)			ESP

- 8, 16, and 32 bit versions
- By convention some registers for special purposes
- Example: ADD EAX, 10
- Other instructions: SUB, AND, etc.

# EFLAGS register

		31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13 12	11	10	9	8	7	6	5	4	3	2	1	0
		0	0	0	0	0	0	0	0	0	0	b	V P	V F	Å	V M	R	0	N T	- О Р L	O F	D	F	F	SF	Z	0	A F	0	P	1	CF
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- Test instructions: TEST EAX, 0
- Conditional JMP instructions: JNZ address

#### Memory: more work space

```
movl %eax, %edx edx = eax; register mode movl $0x123, %edx edx = 0x123; immediate movl 0x123, %edx edx = *(int32_t*)0x123; direct movl (%ebx), %edx edx = *(int32_t*)ebx; indirect movl 4(\%ebx), %edx edx = *(int32_t*)(ebx+4); displaced
```

- Memory instructions: MOV, PUSH, POP, etc
- Most instructions can take a memory address

# Stack memory + operations

#### Example instruction What it does

 pushl %eax
 subl \$4, %esp movl %eax, (%esp)

 popl %eax
 movl (%esp), %eax addl \$4, %esp

 call 0x12345
 pushl %eip (\*) movl \$0x12345, %eip (\*) popl %eip (\*)

 ret
 popl %eip (\*)

- Stack grows down
- Use to implement procedure calls

#### More memory

- 8086 16 registers and 20-bit bus addresses
- The extra 4 bits come segment registers
  - CS: code segment, for EIP
  - SS: stack segment, for SP and BP
  - DS: data segment for load/store via other registers
  - ES: another data segment, destination for string ops
  - For example: CS=4096 to start executing at 65536
- Makes life more complicated
  - Cannot use 16 bit address of stack variable as pointer
  - Pointer arithmetic and array indexing across segment boundaries
  - For a far pointer programmer must include segment reg

#### And more memory

- 80386: 32 bit data and bus addresses
- Now: the transition to 64 bit addresses
- Backwards compatibility:
  - Boots in 16-bit mode, and boot.S switches to 32bit mode
  - Prefix 0x66 gets you 32 bit mode:
    - MOVW = 0x66 MOVW
  - .code32 in boot.S tells assembler to insert 0x66
- 80386 also added virtual memory addresses
  - Topic of lab lecture 3

## I/O space and instructions

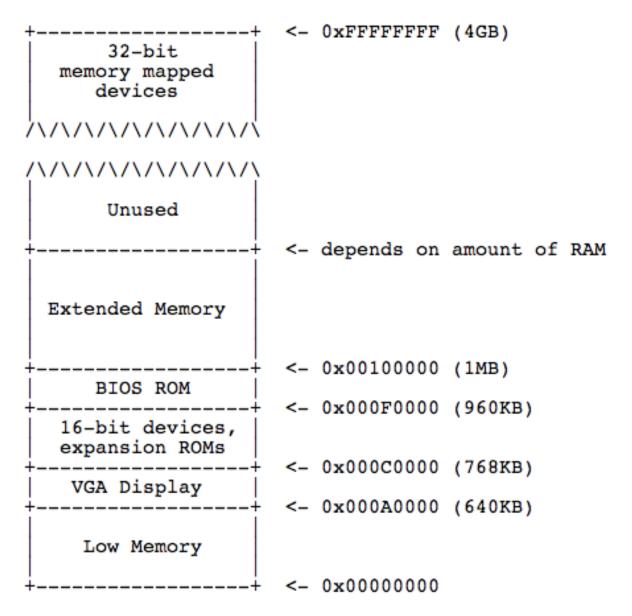
```
#define DATA PORT 0x378
#define STATUS PORT 0x379
#define BUSY 0x80
#define CONTROL PORT 0x37A
#define STROBE 0x01
void
lpt putc(int c)
  /* wait for printer to consume previous byte */
  while((inb(STATUS PORT) & BUSY) == 0)
  /* put the byte on the parallel lines */
  outb(DATA PORT, c);
  /* tell the printer to look at the data */
  outb(CONTROL PORT, STROBE);
  outb(CONTROL_PORT, 0);
```

- 8086: Only 1024 I/O addresses
- Interrupts in lab 3 lecture

## Memory-mapped I/O

- Use normal addresses
  - No need for special instructions
  - No 1024 limit
  - System controller routes to device
- Works like "magic" memory
  - Addressed and accessed like memory
  - But does not behave like memory
  - Reads and writes have "side effects"
  - Read result can change due to external events

## Memory layout



#### x86 instruction set

- Instructions classes:
  - Data movement: MOV, PUSH, POP, ...
  - Arithmetic: TEST, SHL, ADD, ...
  - I/O: IN, OUT, ...
  - Control: JMP, JZ, JNZ, CALL, RET
  - String: REP, MOVSB, ...
  - System: IRET, INT, ...
- Intel architecture manual Volume 2
  - Intel syntax: op dst, src
  - AT&T (gcc/gas) syntax: op src, dst

#### gcc procedure calling conventions

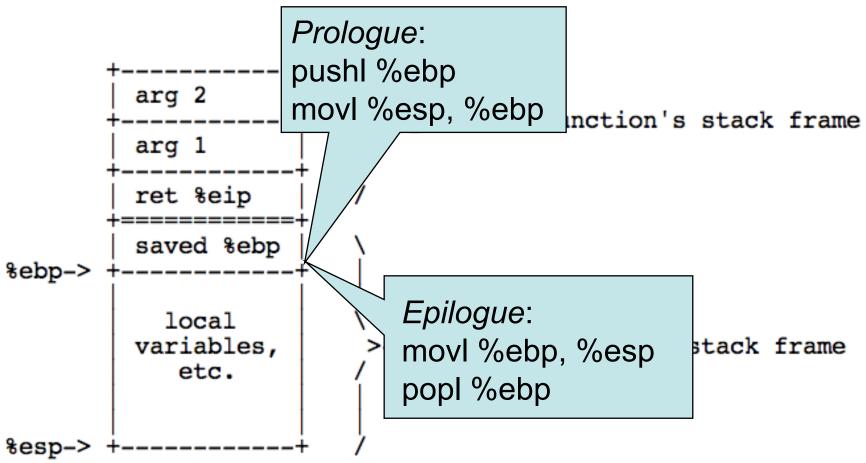
- After CALL instruction:
  - %eip points to first instructions
  - %esp + 4 points at first argument
  - %esp points at return address
- After RET instruction:

Caller saved

- %eip contains return
- %esp point arguments pushed by caller
- %eax contains return value, %ecx, %edx may be trashed
- %ebp, %ebx, %esi, %edi must be as before call

Callee saved

#### gcc does more: EBP



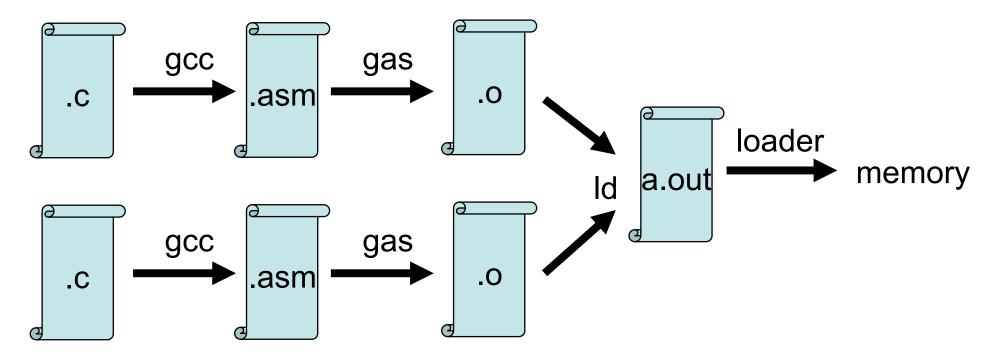
- Saved %ebp's form a chain, can walk stack
- Arguments and locals at fixed offsets from EBP

## Example

```
int main(void) { return f(8)+1; }
int f(int x) { return g(x); }
int g(int x) { return x+3; }
```

```
main:
                        prologue
        pushl %ebp
        movl %esp, %ebp
                         body
        pushl $8
        call f
        addl $1, %eax
                         epilogue
        movl %ebp, %esp
        popl %ebp
        ret
f:
                        prologue
        pushl %ebp
        movl %esp, %ebp
                         body
        pushl 8(%esp)
        call g
                         epilogue
        movl %ebp, %esp
        popl %ebp
        ret
_g:
                        prologue
        pushl %ebp
        movl %esp, %ebp
                         save %ebx
        pushl %ebx
                         body
        mov1 8(%ebp), %ebx
        addl $3, %ebx
        movl %ebx, %eax
                         restore %ebx
        popl %ebx
                         epilogue
        mov1 %ebp, %esp
        popl %ebp
        ret
```

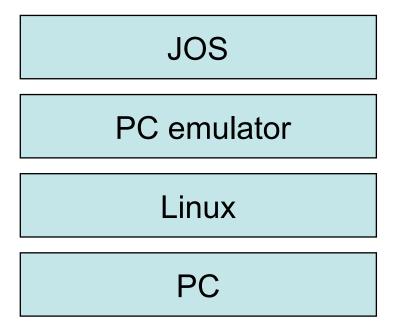
## From C to running program



Compiler, assembler, linker, and loader

## Development using PC emulator

- Bochs PC emulator
  - does what a real PC does
  - Only implemented in software!
- Runs like a normal program on "host" operating system



#### **Emulation of memory**

```
int32_t regs[8];
#define REG_EAX 1;
#define REG_EBX 2;
#define REG_ECX 3;
...
int32_t eip;
int16_t segregs[4];
...
char mem[256*1024*1024];
```

#### **Emulation of CPU**

```
for (;;) {
        read_instruction();
        switch (decode_instruction_opcode()) {
        case OPCODE ADD:
                int src = decode src reg();
                int dst = decode dst reg();
                regs[dst] = regs[dst] + regs[src];
                break;
        case OPCODE SUB:
                int src = decode src reg();
                int dst = decode dst reg();
                regs[dst] = regs[dst] - regs[src];
                break;
        eip += instruction length;
```

#### Emulation x86 memory

```
uint8 t read byte(uint32 t phys addr) {
        if (phys addr < LOW MEMORY)
                return low mem[phys addr];
        else if (phys addr >= 960*KB && phys addr < 1*MB)
                return rom bios[phys addr - 960*KB];
        else if (phys addr >= 1*MB && phys addr < 1*MB+EXT MEMORY) {
                return ext mem[phys addr-1*MB];
        else ...
void write byte(uint32 t phys addr, uint8 t val) {
        if (phys addr < LOW MEMORY)
                low mem[phys addr] = val;
        else if (phys addr >= 960*KB && phys addr < 1*MB)
                ; /* ignore attempted write to ROM! */
        else if (phys addr >= 1*MB && phys addr < 1*MB+EXT MEMORY) {
                ext mem[phys addr-1*MB] = val;
        else ...
```

## **Emulating devices**

- Hard disk: using a file of the host
- VGA display: draw in a host window
- Keyboard: hosts's keyboard API
- Clock chip: host's clock
- Etc.

## Summary

- For lab: PC and x86
- Illustrate several big ideas:
  - Stored program computer
  - Stack
  - Memory-mapped I/O
  - Software = hardware